

Part-turn actuator			Motor									
Type	Operating time for 90° [in seconds]	Max. torque [Nm]	Motor type	Nominal power ¹⁾ P _N [kW]	Speed [rpm]	Nominal current ²⁾ I _N [A]	Max. current ³⁾ I _{max} [A]	Starting current I _A [A]	cos φ	Overcurrent protection device setting [A]	AUMA power class switchgears	
											Contactor	Thyristor
SQR 05.2	8	150	VDOR063-4-0.04	0.04	1,400	0.4	0.4	1.0	0.50	0.4	A1	B1
	11		VDOR063-4-0.02	0.02	1,400	0.4	0.4	1.0	0.50	0.4	A1	B1
	16		SDOR063-4-0.01	0.01	1,400	0.4	0.4	1.0	0.40	0.4	A1	B1
	22		SDOR063-4-0.01	0.01	1,400	0.3	0.3	0.7	0.39	0.3	A1	B1
	32		VDOR063-4-0.06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
SQR 07.2	8	300	VDOR063-4-0.03	0.03	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	11		VDOR063-4-0.03	0.03	1,400	0.4	0.4	1.0	0.43	0.4	A1	B1
	16		SDOR063-4-0.01	0.01	1,400	0.4	0.4	1.0	0.43	0.4	A1	B1
	22		SDOR063-4-0.01	0.01	1,400	0.3	0.3	0.7	0.39	0.3	A1	B1
	32		VDOR063-4-0.10	0.10	1,400	0.8	0.9	2.0	0.48	0.9	A1	B1
SQR 10.2	11	600	SDOR063-4-0.06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	16		SDOR063-4-0.04	0.04	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	22		SDOR063-4-0.02	0.02	1,400	0.5	0.5	1.0	0.48	0.5	A1	B1
	32		SDOR063-4-0.02	0.02	1,400	0.3	0.3	0.7	0.43	0.3	A1	B1
	45		VDOR063-4-0.10	0.10	1,400	0.8	1.0	2.0	0.48	1.0	A1	B1
SQR 12.2	63	900	SDOR063-4-0.06	0.06	1,400	0.8	0.9	2.0	0.48	0.9	A1	B1
	16		SDOR063-4-0.04	0.04	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	22		SDOR063-4-0.04	0.04	1,400	0.5	0.5	1.0	0.48	0.5	A1	B1
	32		VDOR063-4-0.10	0.10	1,400	0.8	0.9	2.0	0.48	0.9	A1	B1
	45		VDOR063-4-0.10	0.10	1,400	0.8	0.9	2.0	0.48	0.9	A1	B1
SQR 14.2	63	1,200	SDOR063-4-0.06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	36		VDOR063-4-0.10	0.10	1,400	0.8	0.9	2.0	0.48	0.9	A1	B1
	48		SDOR063-4-0.06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	72		SDOR063-4-0.06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	100		SDOR063-4-0.06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1

Notes on table

- 1) Nominal power P_N Mechanical power output at motor shaft at running torque of part-turn actuator (corresponds to approx. 35 % of maximum torque).
Consumed electrical power can be calculated using the following formula:
 $P = U \times I \times \cos \varphi \times \sqrt{3}$
- 2) Nominal current I_N Current at running torque
- 3) Max. current I_{max} Current at maximum torque

Notes on installation and sizing

Motor data	Motor data is approximate. Due to usual manufacturing tolerances, there may be deviations from the values given.																
Thermoswitches/PTC thermistors	To protect against overheating, thermoswitches or PTC thermistors are embedded in the motor windings. Actuators without integral controls (AUMA NORM): Thermoswitches or PTC thermistors have to be considered within external controls (refer to terminal plan). Note: Failure to connect thermoswitches or PTC thermistors shall void our warranty for the motor. Rating of thermoswitches <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th colspan="2">AC current</th> <th colspan="2">DC current</th> </tr> </thead> <tbody> <tr> <td colspan="2">250 V, 50 – 60 Hz</td> <td>60 V</td> <td>1.0 A</td> </tr> <tr> <td>cos φ = 1</td> <td>2.5 A</td> <td>42 V</td> <td>1.2 A</td> </tr> <tr> <td>cos φ = 0.6</td> <td>1.6 A</td> <td>24 V</td> <td>1.5 A</td> </tr> </tbody> </table> Actuators with AM or AC integral controls: Thermal motor protection is already integrated.	AC current		DC current		250 V, 50 – 60 Hz		60 V	1.0 A	cos φ = 1	2.5 A	42 V	1.2 A	cos φ = 0.6	1.6 A	24 V	1.5 A
AC current		DC current															
250 V, 50 – 60 Hz		60 V	1.0 A														
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Mains voltage, mains frequency	Permissible variation of the mains voltage: ±10 % Permissible variation of the mains frequency: ±5 %																

Switchgear sizing

For motor operation, reversing contactors (mechanically, electrically and electronically locked) or thyristors (electronically locked) can be used.

Actuators without integral controls (AUMA NORM):

Switchgears are supplied by the customer. We recommend specification of switchgears suitable for their rated operating power/motor power in compliance with the assigned AUMA power class.

Switchgear assignment to AUMA power classes:

AUMA power class	Reversing contactor Rated power according to IEC 60947-4-1 AC-3	Reversing contactor motor power according to UL/CSA at	
	400 V AC	480 V AC	600 V AC
A1	4.0 kW	5.0 hp	5.0 hp
A2	7.5 kW	10 hp	10 hp
A3	15 kW	20 hp	25 hp
A4	30 kW	60 hp	60 hp
A5	55 kW	75 hp	100 hp

AUMA power class	Thyristor Rated current according to EN 60947-4-2 AC-53a
	400 V AC
B1	6 A
B2	8.5 A
B3	16 A

Actuators with AM or AC integral controls:

Required switchgear in power classes A1 – A3 or B1 – B3 are directly integrated in AM or AC controls.
Switch gear in power classes A4/A5 additionally require the control box.